

**AMENDMENTS TO THE CLAIMS**

1. (Currently amended) A device for generating a composite movement comprising:  
          , ~~in~~ a first movement section ~~(L1)~~ having a linear movement running in a longitudinal direction; ~~(4)~~ and, in            a subsequent second movement section ~~(L2)~~ having a predetermined transverse movement ~~(40)~~ including a component perpendicular to the longitudinal direction ~~(4)~~;            -wherein said device comprising a linear member ~~(2)~~ movably guided in the longitudinal direction ~~(4)~~ and a transverse member ~~(6)~~ movably guided on the linear member ~~(2)~~ along a compensatory movement path ~~(12)~~, said compensatory movement path ~~(12)~~ including directional components in said longitudinal direction ~~(4)~~ and perpendicular thereto, and said transverse member ~~(6)~~ being mechanically forcibly guided within said second movement section ~~(L2)~~ of said linear member ~~(2)~~ in order to execute a relative displacement in said longitudinal direction ~~(4)~~ between said transverse member ~~(6)~~ and said linear member ~~(2)~~ such that, as a consequence of a kinematic superposition of the linear movement and a forcibly guided movement along said compensatory movement path ~~(12)~~, the predetermined transverse movement of said transverse member ~~(6)~~ results.
2. (Currently amended) The device as claimed in claim 1, ~~characterised in that~~ wherein the transverse movement is straight and runs at a predetermined angle  $\beta$  to the longitudinal direction ~~(4)~~.
3. (Currently amended) The device as claimed in ~~either of~~ claims ~~1 or 2~~, ~~characterised in that~~ wherein the compensatory movement path ~~(12)~~ runs in a straight line.

4. (Currently amended) The device as claimed in ~~any of the preceding claims 1~~, ~~characterised in that~~ wherein the transverse movement runs perpendicular to the longitudinal direction ~~(4)~~.
5. (Currently amended) The device as claimed in ~~any of the preceding claim s 1~~, ~~characterised in that~~ wherein the compensatory movement path ~~(12)~~ runs in a straight line at 45° to the longitudinal direction ~~(4)~~.
6. (Currently amended) The device as claimed in claim 5, ~~characterised in that~~ wherein the transverse member ~~(6)~~ is forcibly guided in such a way that, within the second movement section ~~(L2)~~ of the linear member ~~(2)~~ ~~it~~ the transverse member remains absolutely still in the longitudinal direction ~~(4)~~, so that, relative to the linear member ~~(2)~~, it is displaced in the longitudinal direction ~~(4)~~, corresponding to the linear movement thereof, but in the opposite direction.
7. (Currently amended) The device as claimed in ~~any of the preceding claim s 1~~, ~~characterised in that~~ wherein the transverse member ~~(6)~~ is forcibly guided by means of a slide rod ~~(18)~~.
8. (Currently amended) The device as claimed in claims 6 and 7, ~~characterised in that~~ wherein the slide rod ~~(18)~~ is, at a first end, pivotably connected to the transverse member ~~(6)~~ and, at a second end, guided by means of a stationary guide path ~~(26)~~, having one part ~~(28)~~ running in the longitudinal direction ~~(4)~~, corresponding to the first movement section ~~(L1)~~, and one part ~~(32)~~ running perpendicular to the longitudinal direction ~~(4)~~, corresponding to the second movement section ~~(L2)~~.
9. (Currently amended) The device as claimed in claim 8, ~~characterised in that~~ wherein a curved transition portion ~~(30)~~ is provided between the first part ~~(28)~~, running in the longitudinal

direction, and the second part ~~(32)~~, running perpendicular to the longitudinal direction.

10. (Currently amended) The device as claimed in ~~either of claims 8 or 9~~, characterised in that wherein the second end of the slide rod ~~(18)~~ is pivotably connected to a free end ~~(16a)~~ of a pivoting lever ~~(16)~~ which is mounted on the linear member ~~(2)~~ and is connected in a torsionally resistant manner to a control lever ~~(22)~~, the free end of which is guided in the guide path ~~(26)~~.
11. (Currently amended) The device as claimed in ~~any of the preceding claims 1~~, characterised in that wherein a holding and/or gripping means ~~(36)~~ is arranged on the transverse member ~~(6)~~ for holding, picking up and/or putting down an article.